

On a Type of Conircular φ -recurrent Trans-Sasakian Manifolds^{*†}

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Abstract

The object of the present paper is to study on a type of conircular φ -recurrent trans-Sasakian manifolds.

Keywords and Phrases: *Trans-Sasakian manifold, Conircular curvature tensor, Conircular φ -recurrent manifold, Locally φ -symmetric trans-Sasakian manifold, Characteristic vector field.*

1. Introduction

The notion of locally φ -symmetric Sasakian manifold was introduced by T. Takahashi [11] in 1977. φ -recurrent Sasakian manifold was studied by the author [12].

Also J. A. Oubina in 1985 introduced a new class of almost contact metric structures which was a generalization of Sasakian [2], α -Sasakian [5], Kenmotsu [5], β -Kenmotsu [5] and cosymplectic [5] manifolds, which was called trans-Sasakian manifold [6]. After him many authors ([3], [4], [5], [6], [8], [9],

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[†]Dedicated to Late Professor M. C. Chaki on occasion of His Birth Centenary.

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[10]) have studied various type of properties in trans-Sasakian manifold.

The paper is organized as follows. Section 2 is concerned with preliminaries. Section 3 is devoted to the study of concircular φ -recurrent trans-Sasakian manifold which satisfies $\varphi(\text{grad } \alpha) = (2n - 1)\text{grad } \beta$ and proved that such a manifold is an Einstein manifold.

It is shown that in a concircular φ -recurrent trans-Sasakian manifold (M^{2n+1}, g) , $n \geq 1$, the characteristic vector field ξ and the vector field ρ associated to the 1-form A are opposite directional.

2. Preliminaries.

A $(2n + 1)$ dimensional, $(n \geq 1)$ almost contact metric manifold M with almost contact metric structure (φ, ξ, η, g) , where φ is a $(1, 1)$ tensor field, ξ is a vector field, η is a 1-form and g is a compatible Riemannian metric such that

$$\varphi^2 = -I + \eta \otimes \xi, \quad \eta(\xi) = 1, \quad \varphi(\xi) = 0, \quad \eta \circ \varphi = 0 \quad (2.1)$$

$$g(\varphi X, \varphi Y) = g(X, Y) - \eta(X)\eta(Y) \quad (2.2)$$

$$g(X, \varphi Y) = -g(\varphi X, Y), \quad g(X, \xi) = \eta(X), \quad (2.3)$$

for all $X, Y \in \chi(M)$

is called trans-Sasakian manifold [6] if and only if

$$(\nabla_X \varphi)Y = \alpha(g(X, Y)\xi - \eta(Y)X) + \beta(g(\varphi X, Y)\xi - \eta(Y)\varphi X) \quad (2.4)$$

for some smooth functions α and β on M .

From (2.4) it follows that

$$\nabla_X \xi = -\alpha\varphi X + \beta(X - \eta(X)\xi) \quad (2.5)$$

$$(\nabla_X \eta)Y = -\alpha g(\varphi X, Y) + \beta g(\varphi X, \varphi Y). \quad (2.6)$$

In [10], the authors obtained some results which shall be useful for next section. They are

$$R(X, Y)\xi = (\alpha^2 - \beta^2)(\eta(Y)X - \eta(X)Y) + 2\alpha\beta(\eta(Y)\varphi X - \eta(X)\varphi Y) + (Y\alpha)\varphi X - (X\alpha)\varphi Y + (Y\beta)\varphi^2 X - (X\beta)\varphi^2 Y \tag{2.7}$$

$$R(\xi, X)\xi = (\alpha^2 - \beta^2 - \xi\beta)(\eta(X)\xi - X) \tag{2.8}$$

$$2\alpha\beta + \xi\alpha = 0 \tag{2.9}$$

$$S(X, \xi) = (2n(\alpha^2 - \beta^2) - \xi\beta)\eta(X) - (2n - 1)X\beta - (\varphi X)\alpha \tag{2.10}$$

$$Q\xi = (2n(\alpha^2 - \beta^2) - \xi\beta)\xi - (2n - 1)grad \beta + \varphi(grad \alpha). \tag{2.11}$$

When $\varphi(grad \alpha) = (2n - 1)grad \beta$, then (2.10) and (2.11) reduces to

$$S(X, \xi) = 2n(\alpha^2 - \beta^2)\eta(X) \tag{2.12}$$

$$Q\xi = 2n(\alpha^2 - \beta^2)\xi. \tag{2.13}$$

Again a trans-Sasakian manifold is said to be locally φ -symmetric [11] if

$$\varphi^2((\nabla_W R)(X, Y)Z) = 0 \tag{2.14}$$

for all vector fields X, Y, Z, W orthogonal to ξ .

Let us introduce concircular φ -recurrent manifold. A trans-Sasakian manifold is said to be concircular φ -recurrent manifold if there exists a non-zero 1-form A such that

$$\varphi^2((\nabla_W \tilde{C})(X, Y)Z) = A(W)\tilde{C}(X, Y)Z \tag{2.15}$$

for $X, Y, Z, W \in \chi(M)$

where the 1-form A is defined as

$$g(X, \rho) = A(X), \quad \forall X \in \chi(M), \quad (2.16)$$

ρ being the vector field associated to the 1-form A and \tilde{C} is a concircular curvature tensor given by [2]

$$\tilde{C}(X, Y)Z = R(X, Y)Z - \frac{r}{2n(2n+1)}[g(Y, Z)X - g(X, Z)Y] \quad (2.17)$$

where a, b are constants such that $a, b \neq 0$, R is the curvature tensor, S is the Ricci-tensor and r is the scalar curvature.

Also,

$$g(QX, Y) = S(X, Y) \quad (2.18)$$

Q being the symmetric endomorphism of the tangent space at each point corresponding to the Ricci-tensor S .

The above results will be useful in the next section.

3. Concircular φ - recurrent Trans-Sasakian Manifold

In this section we consider a trans-Sasakian manifold which is concircular φ -recurrent. Then by virtue of (2.1) and (2.15) we have

$$-(\nabla_W \tilde{C})(X, Y)Z + \eta((\nabla_W \tilde{C})(X, Y)Z)\xi = A(W)\tilde{C}(X, Y)Z. \quad (3.1)$$

From (3.1) it follows that

$$\begin{aligned} & -g((\nabla_W \tilde{C})(X, Y)Z, U) + \eta((\nabla_W \tilde{C})(X, Y)Z)\eta(U) \\ & = A(W)g(\tilde{C}(X, Y)Z, U). \end{aligned} \quad (3.2)$$

Let $\{e_i\}$, $i = 1, 2, \dots, 2n + 1$, be an orthonormal basis of the tangent space at any point of the manifold. Then putting $X = U = e_i$ in (3.2) and taking summation over i , $1 \leq i \leq 2n + 1$, we get

$$\begin{aligned}
 (\nabla_W S)(Y, Z) &= \frac{dr(W)}{2n+1}g(Y, Z) - \frac{dr(W)}{2n(2n+1)}[g(Y, Z) - \eta(Y)\eta(Z)] \\
 &\quad - A(W)[S(Y, Z) - \frac{r}{2n+1}g(Y, Z)].
 \end{aligned}
 \tag{3.3}$$

Replacing Z by ξ and using (2.1), (2.3) and (2.12) we obtain

$$(\nabla_W S)(Y, \xi) = \left\{ \frac{dr(W)}{2n+1} - A(W)[2n(\alpha^2 - \beta^2) - \frac{r}{2n+1}] \right\} \eta(Y).
 \tag{3.4}$$

Now we know

$$(\nabla_W S)(Y, \xi) = \nabla_W S(Y, \xi) - S(\nabla_W Y, \xi) - S(Y, \nabla_W \xi).
 \tag{3.5}$$

Using (2.5) and (2.12) in the above relation (3.5) we get, after a brief calculation

$$\begin{aligned}
 (\nabla_W S)(Y, \xi) &= 2n(\alpha^2 - \beta^2)[- \alpha g(\varphi W, Y) + \beta g(W, Y)] \\
 &\quad + \alpha S(Y, \varphi W) - \beta S(Y, W).
 \end{aligned}
 \tag{3.6}$$

Using (3.6) in (3.4) we have

$$\begin{aligned}
 &2n(\alpha^2 - \beta^2)[- \alpha g(\varphi W, Y) + \beta g(W, Y)] + \alpha S(Y, \varphi W) - \beta S(Y, W) \\
 &= \left\{ \frac{dr(W)}{2n+1} - A(W)[2n(\alpha^2 - \beta^2) - \frac{r}{2n+1}] \right\} \eta(Y).
 \end{aligned}
 \tag{3.7}$$

Replacing Y and W by φY and φW respectively, we obtain

$$S(Y, W) = 2n(\alpha^2 - \beta^2)g(Y, W)
 \tag{3.8}$$

and

$$S(\varphi Y, W) = 2n(\alpha^2 - \beta^2)g(\varphi Y, W).
 \tag{3.9}$$

Hence we can state the following:

Theorem 3.1. *A conircular φ -recurrent trans - Sasakian manifold (M^{2n+1}, g) satisfying $\varphi(\text{grad}\alpha) = (2n - 1)\text{grad}\beta$, is an Einstein manifold.*

Now from (3.1) and (2.16) we have

$$\begin{aligned}
 (\nabla_W R)(X, Y)Z &= \eta((\nabla_W R)(X, Y)Z)\xi - A(W)R(X, Y)Z \\
 &\quad + \frac{dr(W)}{2n(2n+1)}[g(Y, Z)X - g(X, Z)Y \\
 &\quad - g(Y, Z)\eta(X)\xi + g(X, Z)\eta(Y)\xi] \\
 &\quad + \frac{r}{2n(2n+1)}A(W)[g(Y, Z)X - g(X, Z)Y]. \tag{3.10}
 \end{aligned}$$

Using Bianchi's identity in (3.10) we obtain

$$\begin{aligned}
 A(W)\eta(R(X, Y)Z) + A(X)\eta(R(Y, W)Z) + A(Y)\eta(R(W, X)Z) \\
 &= \frac{r}{2n(2n+1)}A(W)[g(Y, Z)\eta(X) - g(X, Z)\eta(Y)] \\
 &\quad + \frac{r}{2n(2n+1)}A(X)[g(W, Z)\eta(Y) - g(Y, Z)\eta(W)] \\
 &\quad + \frac{r}{2n(2n+1)}A(Y)[g(X, Z)\eta(W) - g(W, Z)\eta(X)]. \tag{3.11}
 \end{aligned}$$

Putting $Y = Z = \{e_i\}$, where e_i be an orthonormal basis of the tangent space at any point of the manifold, in (3.11) and taking summation over i , $1 \leq i \leq 2n + 1$, we get

$$A(W) + A(X) = -\frac{1}{2n}[A(X)\eta(W) - A(W)\eta(X)]. \tag{3.12}$$

Putting again $X = \xi$ and using (2.1) and (2.3) we obtain

$$A(W) = -\frac{1}{2n-1}\eta(\rho)\eta(W) \tag{3.13}$$

for any vector field W and ρ being the vector field associated to the 1-form A , defined as (2.16). Thus we can state the following theorem:

Theorem 3.2. *In a concircular φ -recurrent trans-Sasakian manifold (M^{2n+1}, g) , $n \geq 1$, the characteristic vector field ξ and the vector field ρ associated to the 1-form A are opposite directional and the 1-form A is given by*

$$(2n - 1)A(W) = -\eta(\rho)\eta(W) \quad \forall W \in \chi(M).$$

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